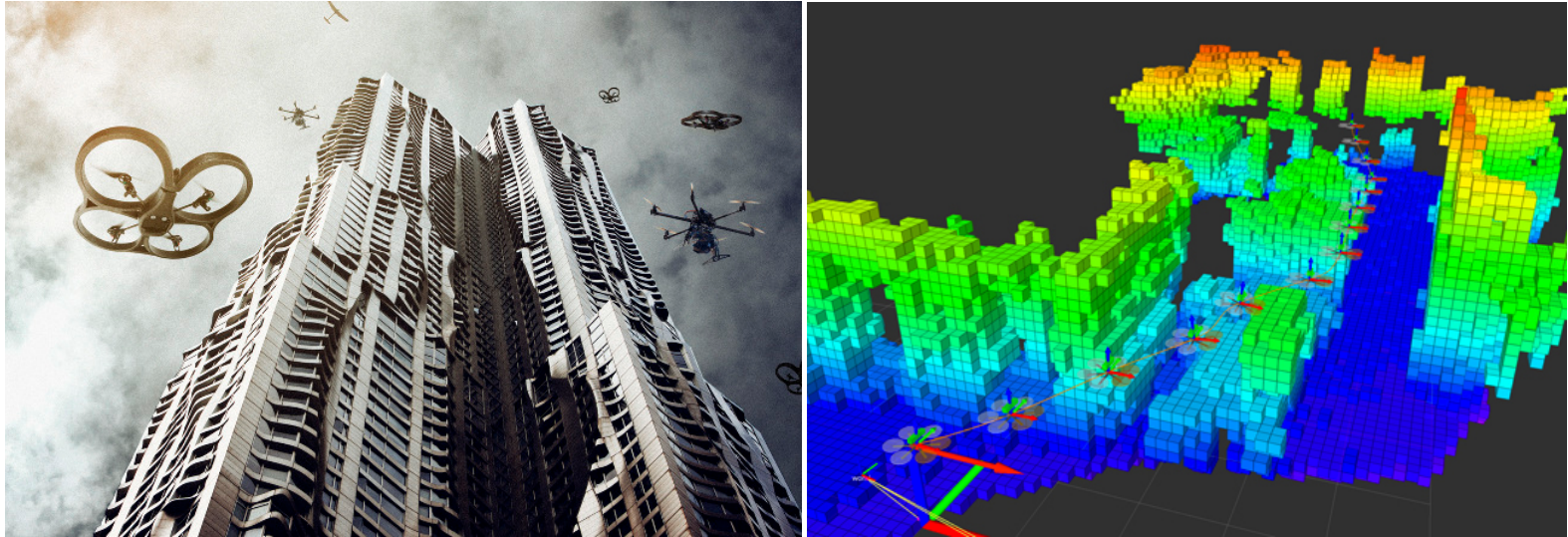# Collaborative Multi-Robot Aerial Autonomous Navigation and 3D Reconstruction

Interested in **collaborative multi-robot perception**? Contact us!

Numerous algorithms to implement and examine on real robots (quadortors), so much to learn - **are you up for the challenge**?

- Pose estimation and 3D reconstruction
- Collaborative RGBD sensing
- Autonomous navigation in unknown environments
- Online decision making under uncertainty

For more information contact us and visit ANPL website (Google it!)

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